



# Introduction to Uncertainty Quantification

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**RTO-AVT-VKI Short Course**

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**Stanford CA, USA**

# Objectives

- ▶ **Introduce** Uncertainty Quantification
  - ▶ Definitions and motivations
  - ▶ Classification of various techniques
  - ▶ Identify different types of uncertainties

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  - ▶ Fluid dynamics: variability in high speed flows
  - ▶ Autoignition: effect of reaction rate uncertainties
  - ▶ Heat transfer: material property uncertainty

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  - ▶ Fluid dynamics: variability in high speed flows
  - ▶ Autoignition: effect of reaction rate uncertainties
  - ▶ Heat transfer: material property uncertainty
- ▶ **Convey** the challenges and the opportunity in UQ Science

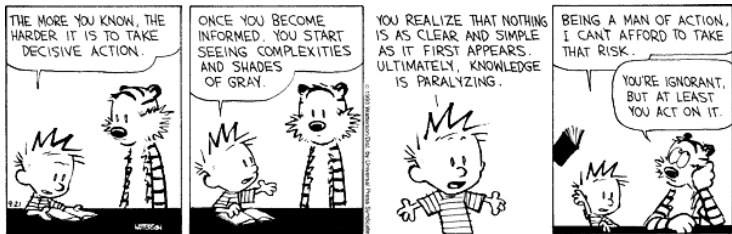


# Outline

1. Why Uncertainty Quantification?
2. Definitions
3. Computations Under Uncertainty
4. Probabilistic Uncertainty Propagation
5. Examples

# Part I

## Why Uncertainty Quantification?



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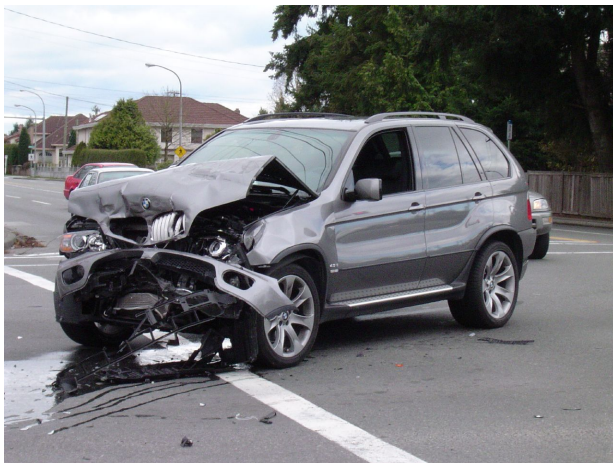
*Uncertainty quantification (UQ) is the science of **quantitative characterization** and reduction of **uncertainties** in applications. It tries to determine how likely certain outcomes are if some aspects of the system are **not exactly known**.*

*An example would be to predict the acceleration of a human body in a head-on crash with another car: even if we exactly knew the speed, small differences in the manufacturing of individual cars, how tightly every bolt has been tightened, etc, will lead to different results that can only be predicted in a statistical sense. [...]*

# Why Uncertainty Quantification?

## Decision Making

- ▶ UQ is critical in identifying the **confidence in an outcome**
- ▶ Provides basis for **certification** in high-consequence decisions



# Why Uncertainty Quantification?

## Validation

- ▶ UQ is a fundamental component of model validation
- ▶ Required to identify the effect **limited knowledge** in inputs of the simulations



Experiments



Simulations

# Why Uncertainty Quantification?

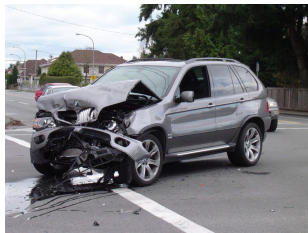
## Validation

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cm

Controlled tests



Real World



# Why Uncertainty Quantification?

## Robust Design

- ▶ System performance are unchanged (stable) when exposed to uncertainties in the operating conditions.
- ▶ **Optimization Under Uncertainty** is a powerful tool for managing the tradeoffs between optimal performance and performance stability.

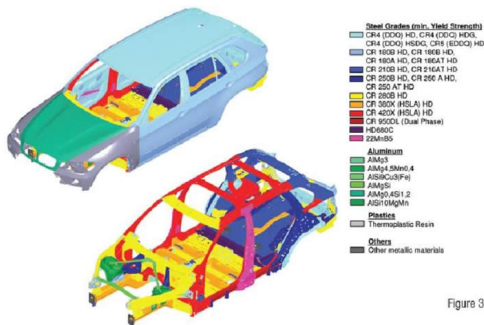


Figure 3

# Why Uncertainty Quantification?

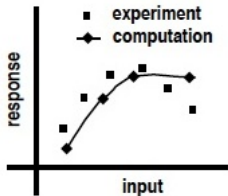
## A simplistic view

- ▶ In spite of the wide spread use of Modeling and Simulation (M&S) tools it remains difficult to provide objective **confidence levels** in the quantitative information obtained from numerical predictions
- ▶ One of the main objective is to provide **error bars** on the simulations results

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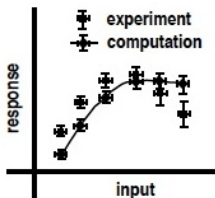
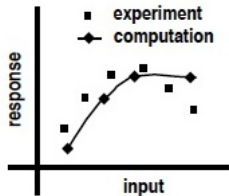
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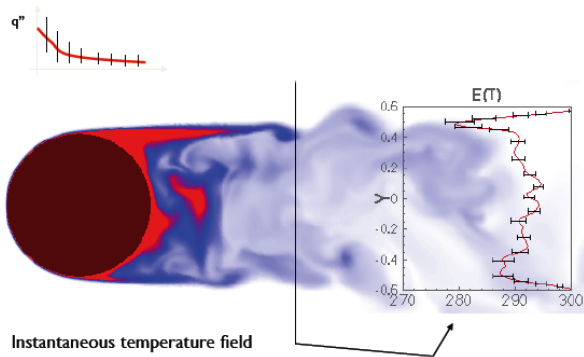


# Why Uncertainty Quantification?

## Error Bars

The objective is to replace the subjective notion of **confidence** with a mathematical rigorous measure

Unsteady turbulent heat convection with uncertain wall heating

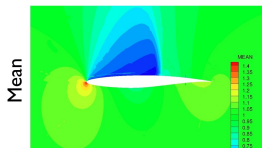


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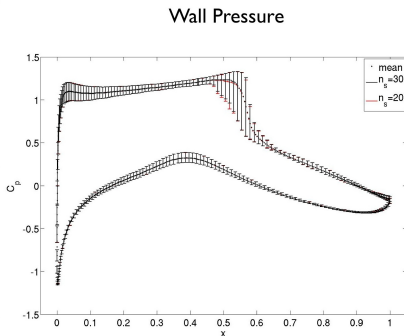
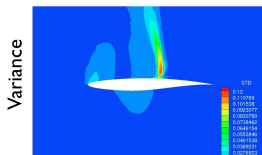
## Error Bars

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## Transonic airfoil with uncertain flight conditions



Pressure Field



## Why do we care about V&V and uncertainty?

- Prefer not to be this guy →
  - Expediency > intellectual integrity
  - No understanding of risks
- Natural part of scientific method
  - Observation
  - Hypothesis
  - Prediction
  - Test



← V&V goes here

- Besides, we all know:  $\frac{BEM}{VLC} \notin \mathbb{R}$

← formerly a BAC



# Part II

## Definitions

"As we know there are known knowns.  
There are things we know we know.  
We also know there are known unknowns.  
That is to say, we know there are some things we do not know.  
But there are also unknown unknowns,  
The ones we don't know we don't know."

D. Rumsfeld, Feb. 12, 2002, Department of Defense news briefing





# Verification and Validation

## Definitions

The American Institute for Aeronautics and Astronautics (AIAA) has developed the “Guide for the Verification and Validation (V&V) of Computational Fluid Dynamics Simulations” (1998)

What is V&V?

- ▶ **Verification**: The process of determining that a model implementation accurately represents the developer's conceptual description of the model.
  
- ▶ **Validation**: The process of determining the degree to which a model is an accurate representation of the real world for the intended uses of the model

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- ▶ **Validation**: The process of determining the degree to which a model is an accurate representation of the real world for the intended uses of the model  
“**are we solving the *correct* equations?**” – it is an exercise in *physics*

# Errors vs. Uncertainties

## Definitions

The AIAA “Guide for the Verification and Validation (V&V) of CFD Simulations” (1998) defines

- ▶ **errors** as recognisable deficiencies of the models or the algorithms employed
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Well...

- ▶ The definitions are not very *precise*
- ▶ Do not clearly distinguish between the *mathematics* and the *physics*.
- ▶ What is the relation with V&V?

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# Uncertainties

**Aleatory**: it is the physical variability present in the system or its environment.

- ▶ It is not strictly due to a lack of knowledge and cannot be reduced (also referred to as variability, stochastic uncertainty or **irreducible uncertainty**)

# Uncertainties

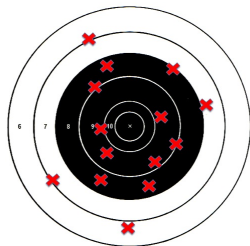
**Aleatory**: it is the physical variability present in the system or its environment.

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- ▶ Examples are: material properties, operating conditions manufacturing tolerances, etc.

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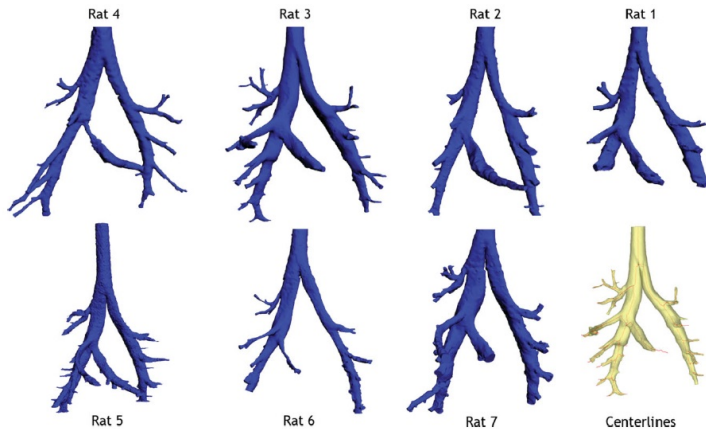
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- ▶ It is naturally defined in a probabilistic framework
- ▶ Examples are: material properties, operating conditions manufacturing tolerances, etc.
- ▶ In mathematical modeling it is also studied as **noise**



# Aleatory Uncertainty

Natural variance

Patient-to-patient differences

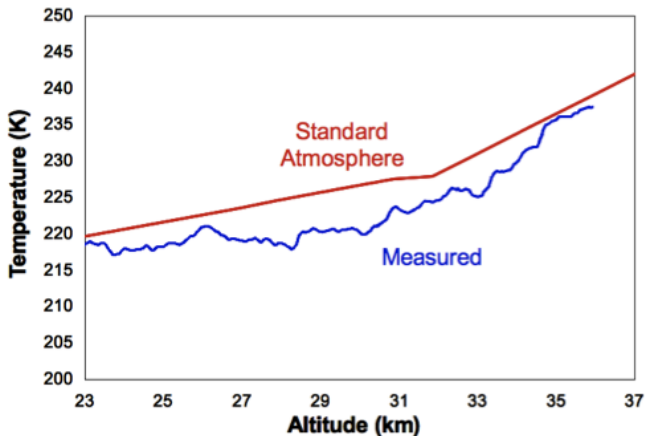


Courtesy of de Backer et al, 2009

# Aleatory Uncertainty

## Flight conditions

Difference between measured (balloon) and expected (Global Reference Atmospheric Model) temperature in the earth atmosphere



# Uncertainties

**Epistemic:** it is a potential deficiency that is due to a lack of knowledge

- ▶ It can arise from assumptions introduced in the derivation of the mathematical model (it is also called **reducible uncertainty** or incertitude)
- ▶ Examples are: turbulence model assumptions or surrogate chemical models

# Uncertainties

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- ▶ Examples are: turbulence model assumptions or surrogate chemical models
- ▶ It is **NOT** naturally defined in a probabilistic framework

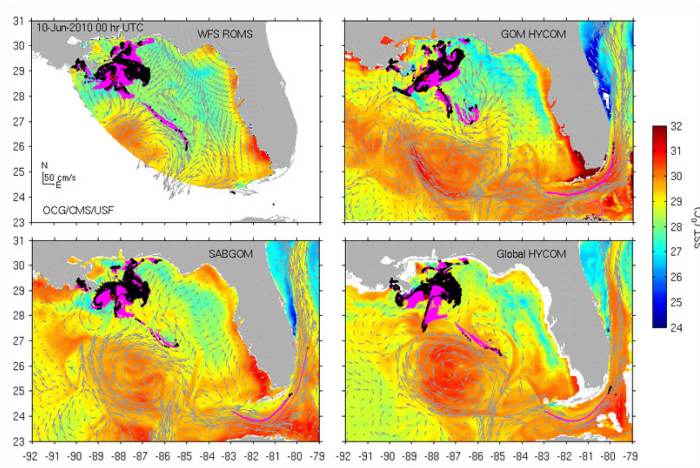




# Epistemic Uncertainty

Model uncertainty

Deepwater Horizon oil tracking **forecast**

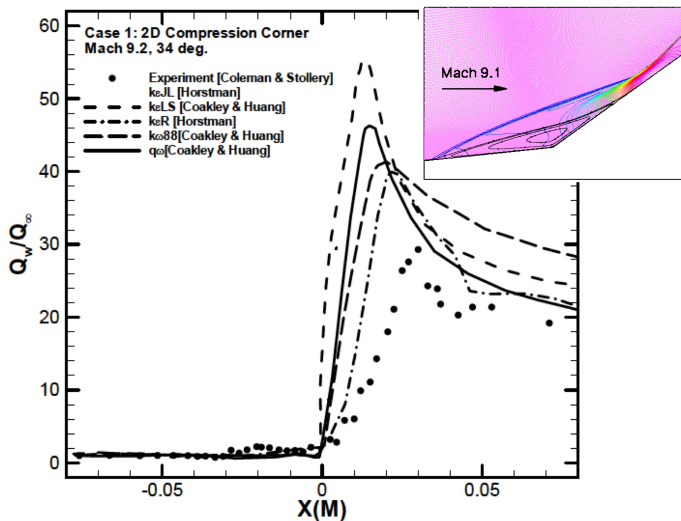


Source: University of Texas Institute of Geophysics

# Epistemic Uncertainty

## Model uncertainty

Predictions of heat flux over a compression ramp



Source: Roy et al, 2007

# Summary

Choose your Uncertain Battles..

- ▶ Uncertainties relate to the **physics of the problem** of interest! not to the errors in the mathematical description/solution...

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- ▶ Uncertainties relate to the **physics of the problem** of interest! not to the errors in the mathematical description/solution...
- ▶ Reducible vs. Irreducible Uncertainty
  - ▶ Epistemic uncertainty **can be reduced** by increasing our knowledge, e.g. performing more experimental investigations and/or developing new physical models.
  - ▶ Aleatory uncertainty **cannot be reduced** as it arises naturally from observations of the system. Additional experiments can only be used to better characterize the variability.

# Sensitivity Analysis vs. UQ

- ▶ Sensitivity analysis (SA) investigates the connection between inputs and outputs of a (computational) model
- ▶ The objective of SA is to identify how the variability in an output quantity of interest ( $q$ ) is connected to an input ( $\xi$ ) in the model; the result is a **sensitivity derivative**  $\partial q / \partial \xi$

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- ▶ **SA  $\in$  UQ**

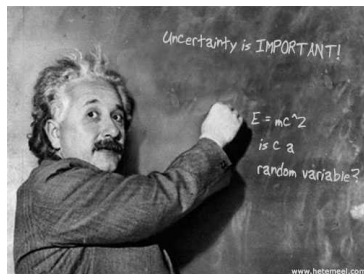


# Part III

## Computations Under Uncertainty = Predictive Simulations

"The significant problems we face cannot be solved  
at the same level of thinking we were at when we created them."

A. Einstein



# Uncertainty Quantification

## Computational Framework

Consider a generic computational model ( $\mathbf{y} \in \mathbb{R}^d$  with  $d$  large)



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How do we handle the uncertainties?

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  - Theoretical arguments
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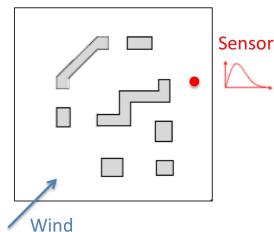
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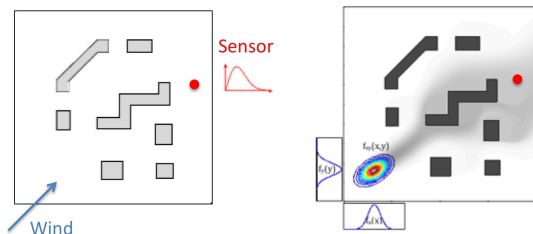
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# Uncertainty definition

## Summary

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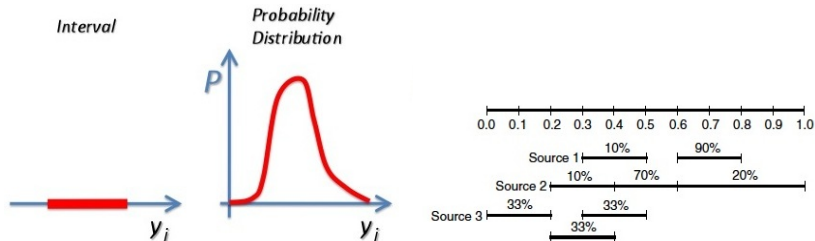
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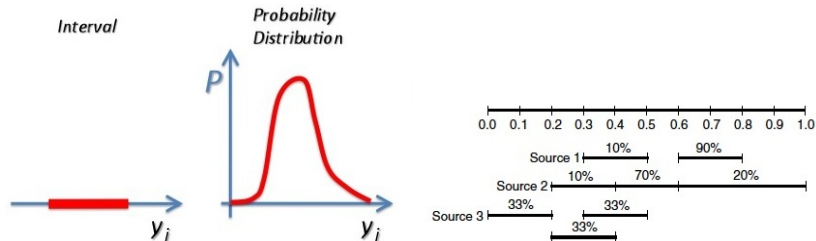
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- ▶ Characterization of the associated level of **knowledge**



- ▶ The mathematical framework for propagating uncertainties is **dependent** on the data representation chosen
  - ▶ In these lectures we focus on probabilistic methods

# Uncertainty Quantification

## Computational Framework

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# Probabilistic Uncertainty Propagation

Perform simulations accounting for the uncertainty represented as randomness

- ▶ Define an abstract probability space  $(\Omega, \mathcal{A}, \mathcal{P})$
- ▶ Introduce uncertain input as **random quantities**  $\mathbf{y}(\omega), \omega \in \Omega$

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Remark:  $\mathbf{y}$  can affect the boundary conditions, the geometry, the forcing terms or the operator in the computational model.

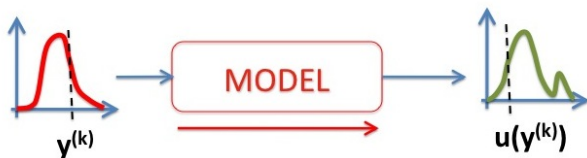
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## Intrusive vs. Non-Intrusive Methodology

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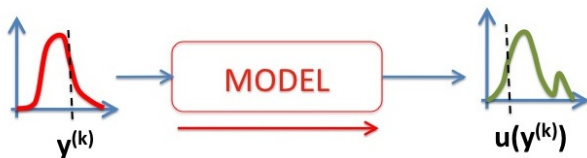
- ▶ **Nonintrusive methods** only require (multiple) solutions of the **original** (deterministic) model



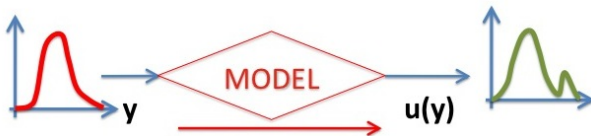
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- ▶ **Intrusive methods** require the formulation and solution of a **stochastic** version of the original model



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## Intrusive vs. Non-Intrusive Methodology

- ▶ **Nonintrusive methods** only require (multiple) solutions of the **original** (deterministic) model
  - + Simple extension of the "conventional" simulation paradigm
  - + Embarrassingly parallel: solutions are independent
  - + Conceptually very simple
  
- ▶ **Intrusive methods** require the formulation and solution of a **stochastic** version of the original model
  - + Exploit the mathematical structure of the problem
  - + Leverage theoretical & algorithmic advancements
  - + Are largely (or entirely) deterministic

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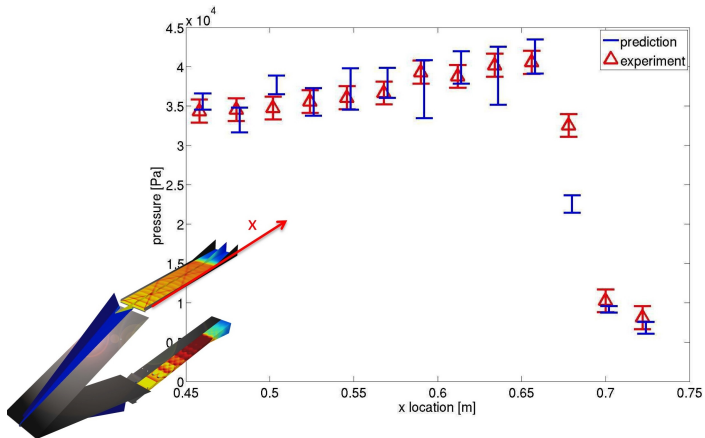
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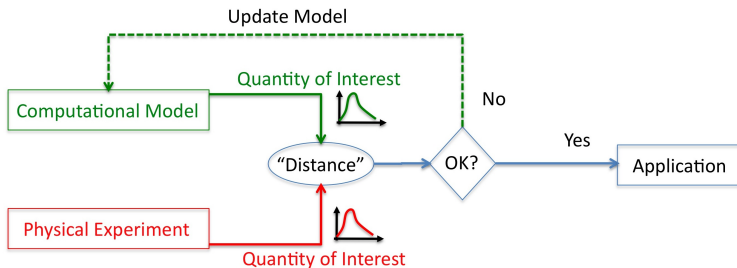
# Certification

- ▶ Quantification of the **confidence**
- ▶ Objective **validity**



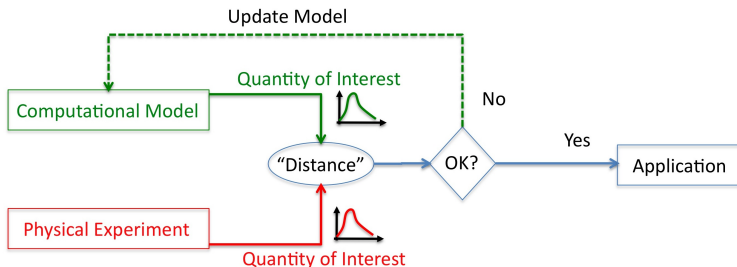
Hypersonic air-breathing vehicle - HyShot II

# Validation



- ▶ Need to define a **validation metric** to compare *uncertain* quantities

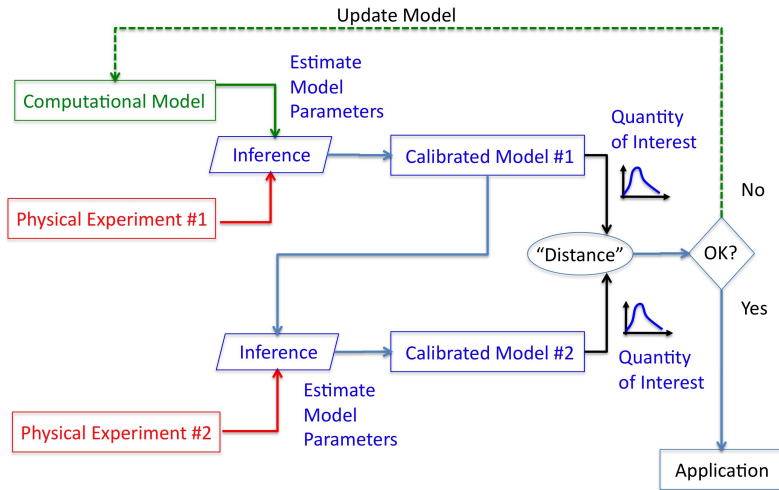
# Validation



- ▶ Need to define a **validation metric** to compare *uncertain* quantities
- ▶ What if the measurements do not have access to the QOI?

# Validation

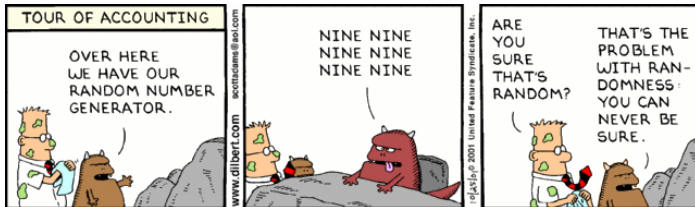
## An Inference Process - PECOS @ UT Austin



- ▶ Simulations are **NOT** compared directly to data!

# Part IV

## Probabilistic Uncertainty Propagation

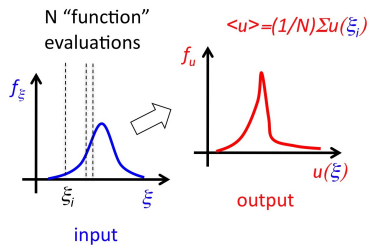


# Uncertainty = Randomness

- ▶ Straightforward Monte Carlo sampling

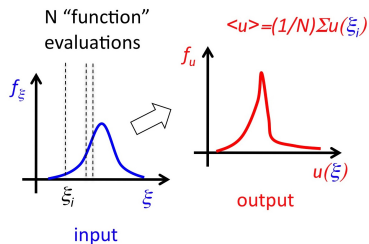
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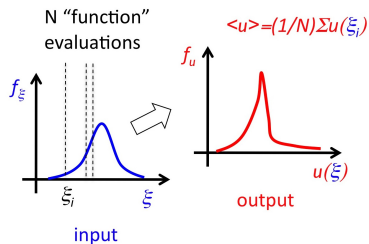


- ▶ ...not feasible with computationally-expensive function evaluations!



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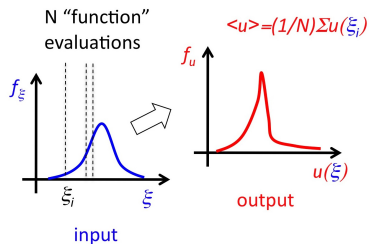


- ▶ Interpret the uncertainties as additional **independent** variables and use approximation theory to represent the solution

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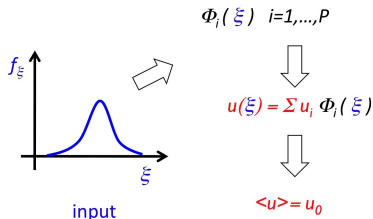
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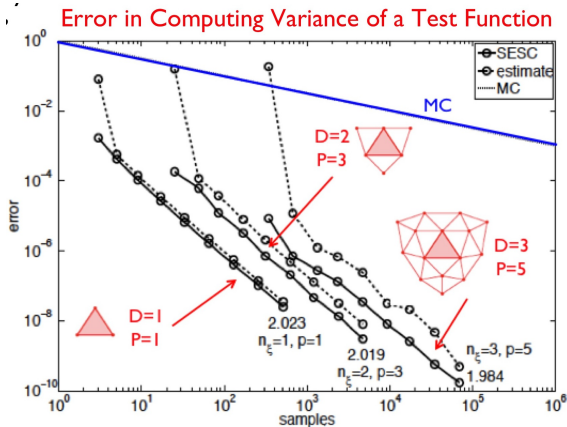
- ▶ Interpret the uncertainties as additional **independent** variables and use approximation theory to represent the solution

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# Uncertainty = Randomness

- ▶ Beyond Monte Carlo
  - ▶ Advanced Sampling: LHS, importance-sampling, quasi-random sequence, ...
  - ▶ Intrusive methods: Polynomial chaos
  - ▶ Non-intrusive approaches: Stochastic collocation



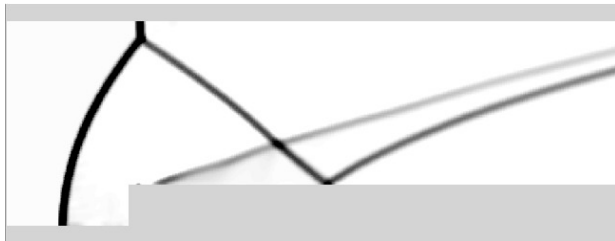
# Part V

## Examples



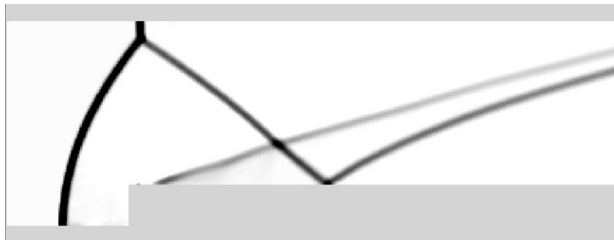
# Fluid Dynamics of High Speed Flows

Known Inflow Mach Number (deterministic simulation)



# Fluid Dynamics of High Speed Flows

Known Inflow Mach Number (deterministic simulation)



Uncertain Inflow Mach Number (average of stochastic simulations)



# Uncertainty in Ignition Delay Time

Michael Mueller - ME470 Final Project

- ▶ Determination of Ignition Delay Time is an important design consideration
- ▶ Accumulation of radicals starts chain reaction causing sudden ignition of mixture
- ▶ **What is the effect of uncertainties in reaction rates?**

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  - ▶ Hydrogen chemistry (9 species, 25 elementary reactions)
  - ▶ **What is the uncertainty?**

# Hydrogen Chemistry

## Reaction Rate Uncertainties

- ▶ Rate (and their uncertainties) are available in the literature
- ▶ Modified Arrhenius form  
 $k = AT^n \exp(-E/RT)$
- ▶ The uncertainty factor **UF** is such that  $[k \times UF, k/UF]$  provide *probable* bounds!
- ▶ *Assume* that the reaction rate are **independent, lognormally distributed** r.v.

Reaction	A	n	E	UF
H + O <sub>2</sub> ↔ O + OH	2.64e16	-0.67	71.30	1.5
O + H <sub>2</sub> ↔ H + OH	4.59e4	2.70	26.19	1.3
OH + H <sub>2</sub> ↔ H + H <sub>2</sub> O	1.73e8	1.51	14.35	2.0
OH + OH ↔ O + H <sub>2</sub> O	3.97e4	2.40	-8.83	1.5
H + H + M ↔ H <sub>2</sub> + M	1.78e18	-1.00	0.00	2.0
H + H + H <sub>2</sub> ↔ H <sub>2</sub> + H <sub>2</sub>	9.00e16	-0.60	0.00	2.5
H + H + H <sub>2</sub> O ↔ H <sub>2</sub> + H <sub>2</sub> O	5.62e19	-1.25	0.00	2.0
H + OH + M ↔ H <sub>2</sub> O + M	4.40e22	-2.00	0.00	2.0
H + O + M ↔ OH + M	9.43e18	-1.00	0.00	3.0
O + O + M ↔ O <sub>2</sub> + M	1.20e17	-1.00	0.00	2.0
H + O <sub>2</sub> + M ↔ HO <sub>2</sub> + M	6.33e19	-1.40	0.00	1.2
H <sub>2</sub> + O <sub>2</sub> ↔ HO <sub>2</sub> + H	5.92e5	2.43	223.85	2.0
OH + OH + M ↔ H <sub>2</sub> O <sub>2</sub> + M	2.01e17	-0.58	-9.59	2.5
HO <sub>2</sub> + H ↔ O + H <sub>2</sub> O	3.97e12	0.00	2.81	3.0
HO <sub>2</sub> + H ↔ OH + OH	7.49e13	0.00	2.66	2.0
HO <sub>2</sub> + O ↔ OH + O <sub>2</sub>	4.00e13	0.00	0.00	1.2
HO <sub>2</sub> + OH ↔ H <sub>2</sub> O + O <sub>2</sub>	2.38e13	0.00	-2.09	3.0
	1.00e16	0.00	72.51	3.0
HO <sub>2</sub> + HO <sub>2</sub> ↔ O <sub>2</sub> + H <sub>2</sub> O <sub>2</sub>	1.30e11	0.00	-6.82	1.4
	3.66e14	0.00	50.21	2.5
H <sub>2</sub> O <sub>2</sub> + H ↔ HO <sub>2</sub> + H <sub>2</sub>	6.05e6	2.00	21.76	3.0
H <sub>2</sub> O <sub>2</sub> + H ↔ H <sub>2</sub> O + OH	2.41e13	0.00	16.61	2.0
H <sub>2</sub> O <sub>2</sub> + O ↔ HO <sub>2</sub> + OH	9.63e6	2.00	16.61	3.0
H <sub>2</sub> O <sub>2</sub> + OH ↔ HO <sub>2</sub> + H <sub>2</sub> O	2.00e12	0.00	1.79	2.0
	2.67e41	-7.00	157.32	2.0

# Ignition Delay Time

## Uncertainty Propagation

- ▶ Conditions: Stoichiometric Hydrogen-Air Mixture (29.6% H<sub>2</sub>; 14.8% O<sub>2</sub>); Temperature: 1000 K; Pressure: 1 atm;
- ▶ Non-intrusive LHS Sampling (25 uncertain variables)

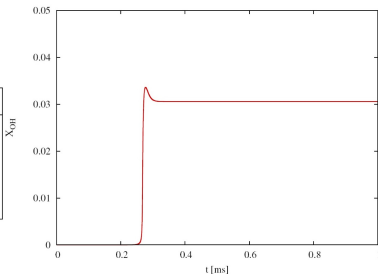
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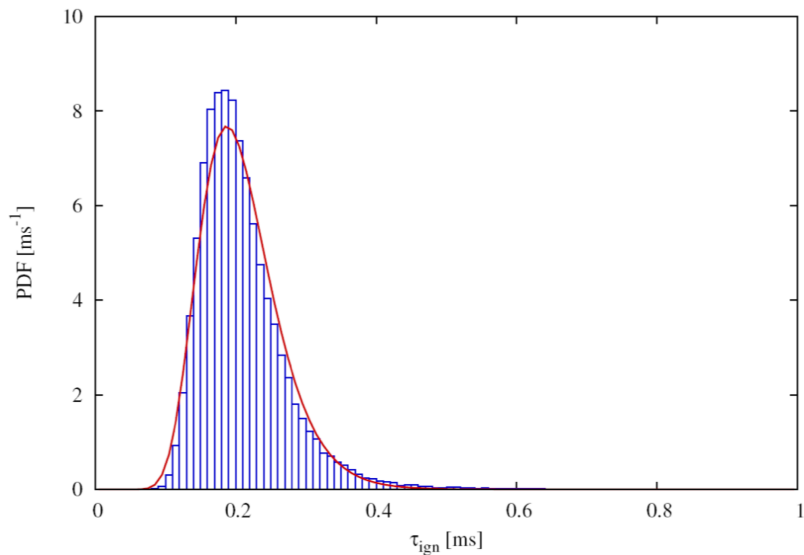
Number of Samples	Mean [ms]	$UF$
100	0.202060	1.7362
1000	0.201304	1.7054
10000	0.201256	1.7039
100000	0.201263	1.7075

One Sample Showing Ignition at ~0.25 ms



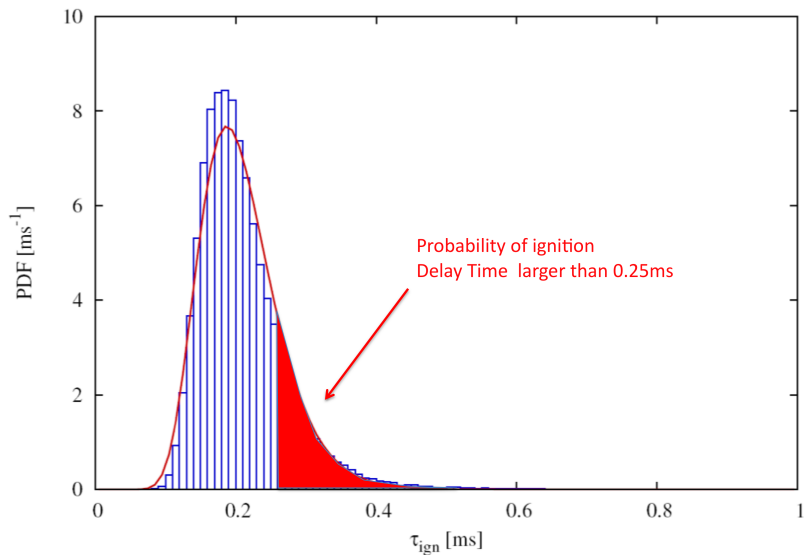
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## Uncertainty Propagation



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## Inverse Problem

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# Ignition Delay Time

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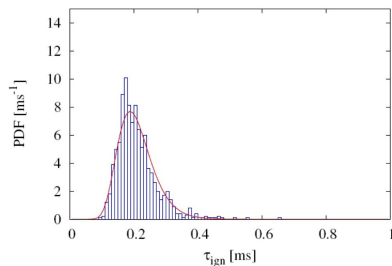
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Quantity	Nominal	Optimal
UF Branching Reaction	1.5	1.29
Mean $\tau_{ign}$ [ms]	0.201304	0.198947
UF $\tau_{ign}$	1.7054	1.4023
Probability of Failure	0.191	0.100

# Ignition Delay Time

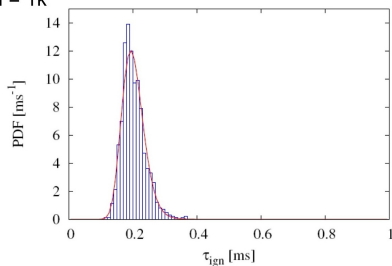
## Uncertainty Propagation

Nomimal



Optimal

N = 1k

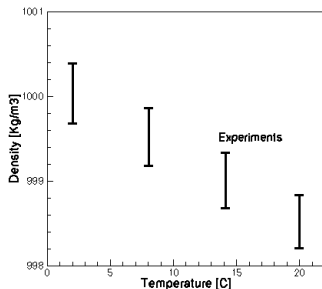
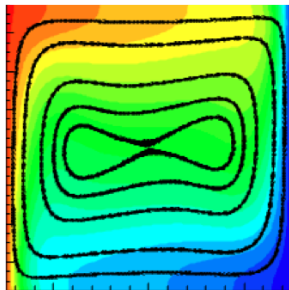


- ▶ Overall uncertainty in the IDT is reduced
- ▶ Failure probability below critical requirement

# Uncertainty in Buoyancy-Driven Convection

Gary Tang - ME470 Final Project

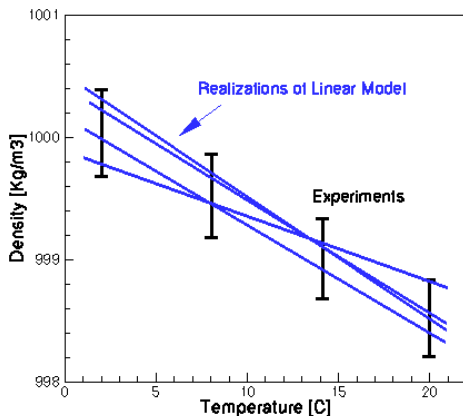
- ▶ Fluid driven by the temperature gradient induced by hot/cold wall.
- ▶ Assume that there is uncertainty in the relationship between temperature and density, with density measured at various temperatures..
- ▶ **What is the average temperature on the bottom wall?**



# Density/Temperature Relationship

## Interpreting the measurements

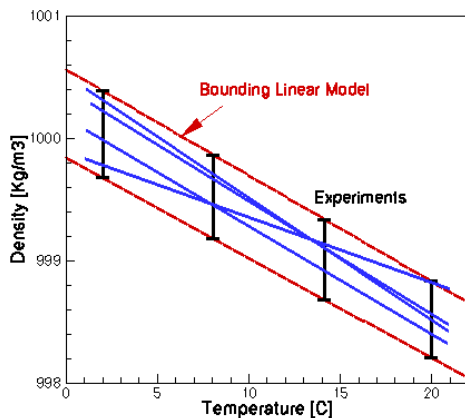
- ▶ A **linear** model appears to be appropriate to capture the experimental scatter!
- ▶ Can build an *uncertain* model with two random variables, constr:



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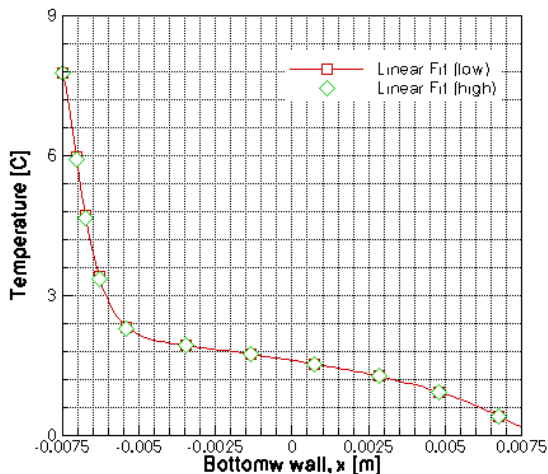
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# Driven Cavity

## Uncertainty Quantification

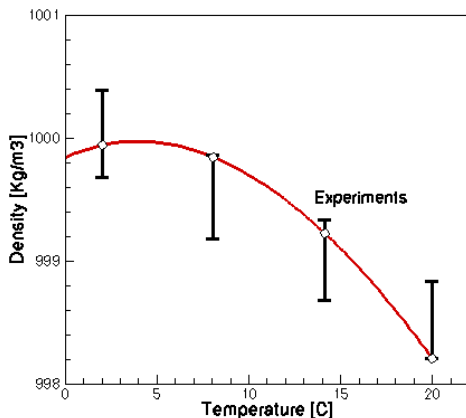
- Variability is limited! No sensitivity!



# Density/Temperature Relationship

## Interpreting the measurements

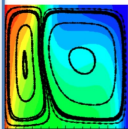
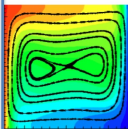
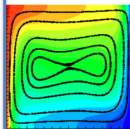
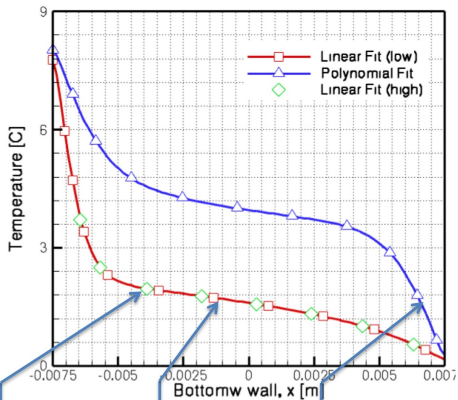
- ▶ *Perfect* experiments would have allowed a precise determination of the density/temperature relationship...



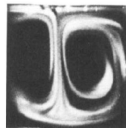


# Driven Cavity

## Uncertainty Quantification



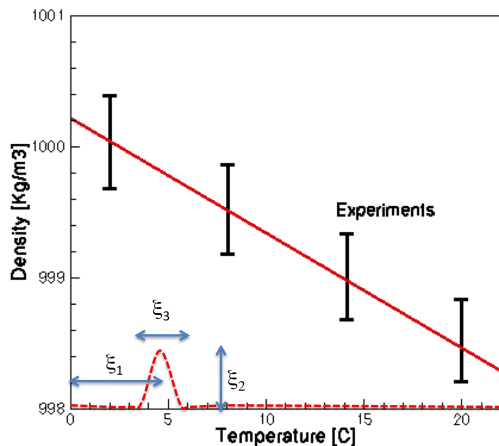
Experiment



# Density/Temperature Relationship

## Interpreting the measurements

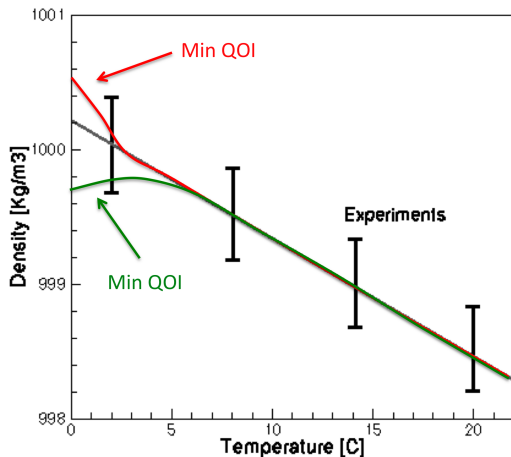
- ▶ Alternative approach (in the absence of perfect experiments) is NOT to rely on the linear model...



# Density/Temperature Relationship

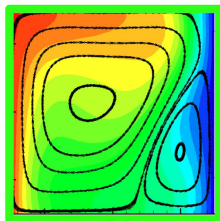
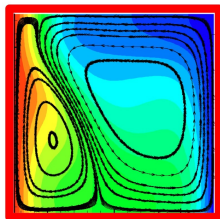
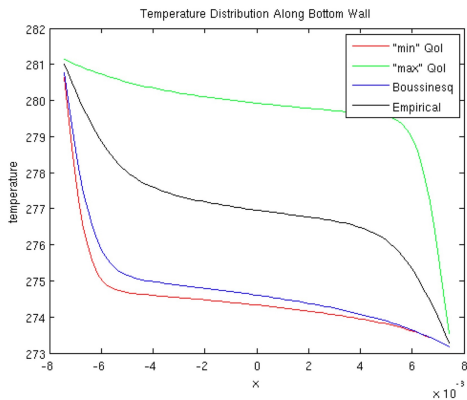
## Interpreting the measurements

- ▶ Perform an **optimization under uncertainty** to find the MIN and MAX average temperature on the bottom wall!



# Driven Cavity

## Uncertainty Quantification



- ▶ The optimization procedure *finds* the density/temperature relationships that lead to MIN and MAX of the average temperature on the bottom wall!

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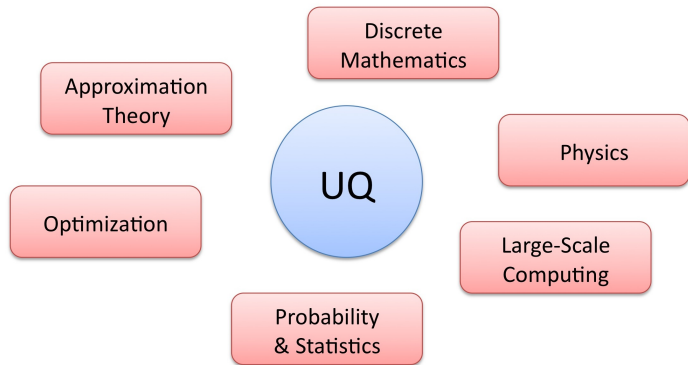


# Concluding

- ▶ Uncertainty Quantification plays a critical role in **Validation!**  
...but there are a lot of other exciting applications of the same methodologies, especially in combination with optimization tools.
- ▶ Applications of UQ to realistic problems remains challenging:
  - ▶ Interpretation and **representation** of the uncertainties
  - ▶ **Algorithmic advances** are still required for costly computations, large number of uncertain inputs, discontinuous responses

# Concluding

an ICME recruiting slide



UQ requires a broad range of skills...

# Thank You



UQ Publications

http://www.stanford.edu/group/uq/uq\_publications.html

STANFORD UNIVERSITY UNCERTAINTY QUANTIFICATION LABORATORY

## UQ Group Publications

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Doctoral Thesis | Journal Papers | Conference Papers | Technical Reports

### Doctoral Thesis

Constantine P. "SPECTRAL METHODS FOR PARAMETERIZED MATRIX EQUATIONS". Institute for Computational and Mathematical Engineering, 2009.

Wang Q. "UNCERTAINTY QUANTIFICATION FOR UNSTEADY FLUID FLOW USING ADJOINT-BASED APPROACHES". Institute for Computational and Mathematical Engineering, 2009.

### Journal Papers

Wang Q., Moyn P., Iaccarino G. "A Rational Interpolation Scheme with Spline Polynomial Rate Extension for Numerical Analysis". Vol. 47(6), pp. 4073-4097, 2010.

P. Petterson, J. Nordstrom, G. Iaccarino. "Boundary Procedures for the Time-Dependent Burgers' Equation under Uncertainty". ACTA Mathematica Scientia, Vol. 30(2), pp. 539-550, 2010.

Chandrasekhar T., Doustan A., Iaccarino G. "Pade-Legendre Approximation for Uncertainty Quantification with Discontinuous Response Surfaces". Journal of Computational Physics, Vol. 228 (9), pp. 7189-7190, 2009.

Petterson P., Iaccarino G., Nordstrom J. "Numerical analysis of the Burgers equation in the context of uncertainty". Journal of Computational Physics, available online. 8/2009. doi: 10.1016/j.jcp.2009.08.019

Constantine P., Doustan A., Iaccarino G. "A Hybrid Collocation/DeltaIn Scheme for Convective Heat Transfer Problems with Stochastic Boundary Conditions". International Journal of Numerical Methods in Engineering, available online. 2/2009. doi: 10.1002/nme.2564.

Wang Q., Moyn P., Iaccarino G. "Minimal Repetition Dynamic Chord-Scaling Algorithm for Uncertainty Adjoint Solution". SIAM Journal of Scientific Computing, Vol. 31, No. 4, pp. 2549-2567, 2009.

Doustan A., Iaccarino G. "A least-squares approximation of partial differential equations with high dimensional random inputs". Journal of Computational Physics, Vol. 229, No. 12, pp. 4339-4345, 2009.

### UPCOMING EVENTS

Spring 2010  
4/6 SAMSI/UQ Interest Group Meeting, NC

4/12-4/15 AIAA NDA Conference, Orlando, FL

4/22-4/23 PSAAP 1ST Review, Stanford

### RECENT PUBLICATIONS ON UQ

**UQ in JCP, CHAME, SINNE**

Numerical approach for quantification of epistemic uncertainty  
2010; Journal of Computational Physics; Jakeman, J., Ebered, H., Xu, D.

Identification of Bayesian posteriors for coefficients of chaos expansion  
2010; Journal of Computational Physics; Armit, N., Ghemawat, S., Sibley, C.

Non-linear model reduction for uncertainty  
Content provided by Scopus

<http://uq.stanford.edu>

RTO-AVT-VKI Short Course

April 15-16, 2011  
Stanford CA, USA